

# Panel Data Analysis II

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*Linear Methods in Causal Inference*

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# Review

- ▶ In the previous class, we discussed the uniqueness of panel data and how it allows us to relax the identification assumption.
- ▶ Two common assumptions: sequential ignorability and strict exogeneity.
- ▶ They are based on different ideal experiments.
- ▶ Under strict exogeneity, we must impose structural restrictions on the DGP.
- ▶ Then, we can rely on the TWFE model and the within estimator to estimate the causal effect.

## From TWFE to DID

- ▶ Suppose there are only two periods, 1 and 2.
- ▶ There are  $N_1$  units in the treatment group ( $i \in \mathcal{T}$ ) and  $N_0$  in the control group ( $i \in \mathcal{C}$ ).
- ▶  $D_{it} = 0$  in period 1 for any  $i$  and  $D_{it} = 1$  in period 2 only for units in the treatment group:

$$Y_{it} = \begin{cases} Y_{it}(1), & \text{if } i \in \mathcal{T} \text{ and } t = 2 \\ Y_{it}(0), & \text{otherwise} \end{cases}$$

- ▶ We maintain the assumptions for the TWFE model:

$$Y_{it} = \mu + \tau D_{it} + \alpha_i + \xi_t + \varepsilon_{it},$$
$$E[\varepsilon_{is} | D_{it}, \alpha_i, \xi_t] = 0 \text{ for any } s.$$

- ▶ There exists a simpler estimator for  $\tau$  in this case

## From TWFE to DID

- ▶ Note that strict exogeneity implies the following:

$$\begin{aligned} & E[Y_{i2}(0) - Y_{i1}(0)|i \in \mathcal{T}] \\ &= E[\mu + \alpha_i + \xi_2 + \varepsilon_{i2} - (\mu + \alpha_i + \xi_1 + \varepsilon_{i1})|i \in \mathcal{T}] \\ &= \xi_2 - \xi_1 \\ &= E[Y_{i2}(0) - Y_{i1}(0)|i \in \mathcal{C}]. \end{aligned}$$

- ▶ This assumption is known as “parallel trends”.
- ▶ It means that without the treatment, the increase (trend) in the outcome would be the same across the two groups.
- ▶ Strict exogeneity is a sufficient condition for parallel trends to hold.
- ▶ This assumption implies that

$$\begin{aligned} & E[Y_{i2}(0)|i \in \mathcal{T}] \\ &= E[Y_{i1}(0)|i \in \mathcal{T}] + E[Y_{i2}(0)|i \in \mathcal{C}] - E[Y_{i1}(0)|i \in \mathcal{C}]. \end{aligned}$$

## From TWFE to DID

- Therefore,

$$\begin{aligned}\tau &= E[Y_{i2}(1) - Y_{i2}(0)|i \in \mathcal{T}] \\ &= E[Y_{i2}(1)|i \in \mathcal{T}] - E[Y_{i2}(0)|i \in \mathcal{T}] \\ &= E[Y_{i2}(1)|i \in \mathcal{T}] - E[Y_{i1}(0)|i \in \mathcal{T}] \\ &\quad - (E[Y_{i2}(0)|i \in \mathcal{C}] - E[Y_{i1}(0)|i \in \mathcal{C}]) \\ &= E[Y_{i2}|i \in \mathcal{T}] - E[Y_{i1}|i \in \mathcal{T}] \\ &\quad - (E[Y_{i2}|i \in \mathcal{C}] - E[Y_{i1}|i \in \mathcal{C}])\end{aligned}$$

- In practice, we estimate  $\tau$  by

$$\hat{\tau}_{DID} = \frac{1}{|\mathcal{T}|} \sum_{i \in \mathcal{T}} Y_{i2} - \frac{1}{|\mathcal{T}|} \sum_{i \in \mathcal{T}} Y_{i1} - \left( \frac{1}{|\mathcal{C}|} \sum_{i \in \mathcal{C}} Y_{i2} - \frac{1}{|\mathcal{C}|} \sum_{i \in \mathcal{C}} Y_{i1} \right).$$

## From TWFE to DID

- ▶ This is known as the difference-in-differences (DID) estimator.
- ▶ We first take the within-unit difference for each  $i$ , and then take another difference between the two average differences.
- ▶ The estimator is motivated by the TWFE model with homogeneous treatment effects.
- ▶ But it is robust to heterogeneous treatment effects.
- ▶ Let's assume that parallel trends holds and denote

$$\tau_{it} = Y_{it}(1) - Y_{it}(0)$$

$$\tau_{ATT,t} = E[\tau_{it} | i \in \mathcal{T}].$$

- ▶ We can show that

$$E[\hat{\tau}_{DID}] = E[Y_{i2}(1) - Y_{i2}(0) | i \in \mathcal{T}] = \tau_{ATT,2}.$$

- ▶ Moreover,  $\hat{\tau}_{DID} = \hat{\tau}_{TWFE}$ .

## Validate parallel trends

- ▶ As an estimator, DID requires only parallel trends rather than strict exogeneity.
- ▶ The assumption allows us to impute the counterfactual for the treated observations.
- ▶ It is not directly testable since the definition involves  $E[Y_{i2}(0)|i \in \mathcal{T}]$ , which is not observable.
- ▶ But we can test its validity indirectly.
- ▶ Suppose we have another pre-treatment period, period 0.
- ▶ If the trends are parallel between periods 1 and 2, it is reasonable to expect them to be parallel between 0 and 1:

$$\begin{aligned} & E[Y_{i1}(0)|i \in \mathcal{T}] - E[Y_{i0}(0)|i \in \mathcal{T}] \\ &= E[Y_{i1}(0)|i \in \mathcal{C}] - E[Y_{i0}(0)|i \in \mathcal{C}]. \end{aligned}$$

- ▶ In finite sample, it implies that

$$\frac{1}{|\mathcal{T}|} \sum_{i \in \mathcal{T}} Y_{i1} - \frac{1}{|\mathcal{T}|} \sum_{i \in \mathcal{T}} Y_{i0} - \left( \frac{1}{|\mathcal{C}|} \sum_{i \in \mathcal{C}} Y_{i1} - \frac{1}{|\mathcal{C}|} \sum_{i \in \mathcal{C}} Y_{i0} \right) \approx 0.$$

## Validate parallel trends

- ▶ Parallel trends may be more plausible once we focus on a smaller group:

$$\begin{aligned} E[Y_{i2}(0) - Y_{i1}(0) | i \in \mathcal{T}, \mathbf{X}_i = \mathbf{x}] \\ = E[Y_{i2}(0) - Y_{i1}(0) | i \in \mathcal{C}, \mathbf{X}_i = \mathbf{x}]. \end{aligned}$$

- ▶ This is known as “conditional parallel trends”.
- ▶ Let's define  $D_i = \mathbf{1}\{i \in \mathcal{T}\}$  and  $\Delta Y_i(D_i) = Y_{i2}(D_i) - Y_{i1}(D_i)$ .
- ▶ The condition that  $E[\Delta Y_i(0) | D_i = 1, \mathbf{X}_i = \mathbf{x}] = E[\Delta Y_i(0) | D_i = 0, \mathbf{X}_i = \mathbf{x}]$  is similar to unconfoundedness.
- ▶ It is sufficient for identifying the ATT via the IPW estimators:

$$\hat{\tau}_{SDID} = \frac{1}{|\mathcal{T}|} \sum_{i \in \mathcal{T}} \Delta Y_i - \frac{1}{|\mathcal{C}|} \sum_{i \in \mathcal{C}} \frac{\hat{g}(\mathbf{X}_i) \Delta Y_i}{1 - \hat{g}(\mathbf{X}_i)}.$$

- ▶ This is the semiparametric DID estimator in Abadie (2005).



## Multi-period DID

- ▶ We can extend the analysis to datasets with multiple periods.
- ▶ Suppose there are  $T_0$  pre-treatment periods and  $T_1$  post-treatment periods.
- ▶ For any  $t \geq T_0 + 1$ ,

$$\begin{aligned}\hat{\tau}_{DID,t} &= \frac{1}{|\mathcal{T}|} \sum_{i \in \mathcal{T}} Y_{it} - \frac{1}{|\mathcal{T}|T_0} \sum_{i \in \mathcal{T}} \sum_{s=1}^{T_0} Y_{is} \\ &\quad - \left( \frac{1}{|\mathcal{C}|} \sum_{i \in \mathcal{C}} Y_{it} - \frac{1}{|\mathcal{C}|T_0} \sum_{i \in \mathcal{C}} \sum_{s=1}^{T_0} Y_{is} \right)\end{aligned}$$

- ▶ We can then average over all the periods under treatment:

$$\hat{\tau}_{DID} = \frac{1}{T_1} \sum_{t=T_0+1}^T \hat{\tau}_{DID,t}.$$

- ▶ We can similarly show that  $E[\hat{\tau}_{DID,t}] = \tau_t$  and  $E[\hat{\tau}_{DID}] = \tau$ .

## Multi-period DID

- ▶ The previous estimator is equivalent to the following regression model:

$$Y_{it} = \mu + \sum_{s=1}^T \tau_s \mathbf{1}\{t = s\} \mathbf{1}\{i \in \mathcal{T}\} + \alpha_i + \xi_t + \varepsilon_{it}.$$

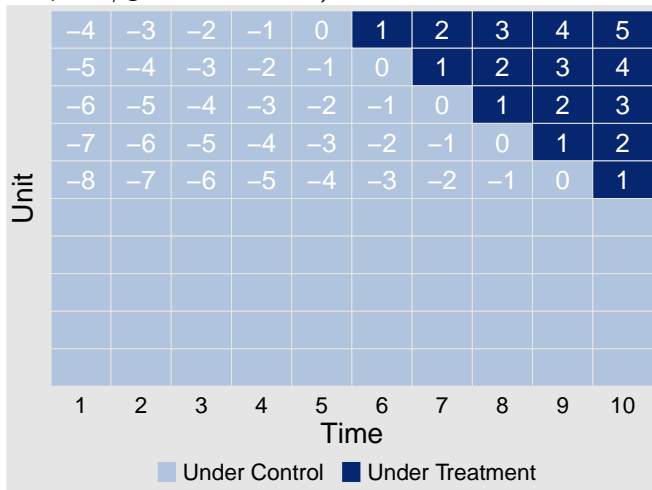
- ▶ For each treated unit, we control for the “leads and lags” of the treatment indicator on the right hand side.
- ▶ This is known as an “event study” model in the literature
- ▶ We can show that  $\hat{\tau}_t = \hat{\tau}_{DID,t}$  for  $t \geq T_0 + 1$  and  $E[\hat{\tau}_t] = 0$  for  $t \leq T_0$ .
- ▶ It generalizes our test for parallel trends in the two-period case.

## Summary

- ▶ We say the data have a DID structure when all the treated units become under treatment from the same period.
- ▶ We can use the TWFE model to estimate the ATT, or use the event study method to estimate the ATT in any post-treatment period.
- ▶ Their results are identical to those from the DID estimator and robust to the heterogeneity in treatment effects.
- ▶ Both the TWFE and the event study models are justified by strict exogeneity, while the DID estimator only requires (conditional) parallel trends.
- ▶ Such an equivalence will break down when the data have a more complex structure.

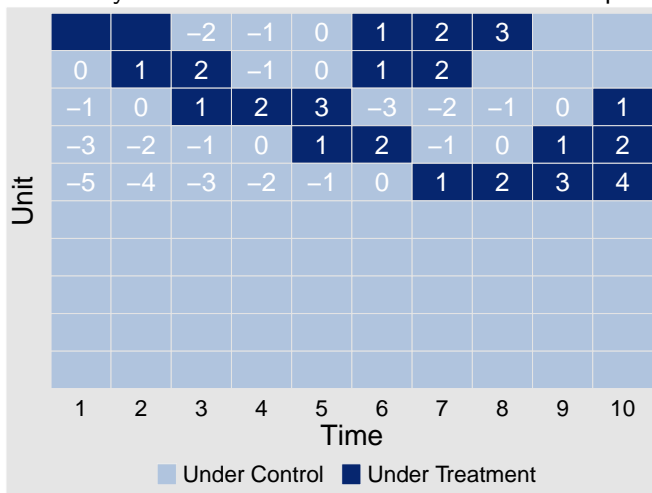
# Complex data structure

- ▶ Possibility I: once treated, always treated (staggered adoption/generalized DID).



## Complex data structure

- Possibility II: treatment switches on and off over periods.



## Caveats of the TWFE model

- ▶ In either case, the within estimator from the TWFE model is inconsistent for the ATT.
- ▶ This problem was identified by a series of papers at the same time (Goodman-Bacon 2018; Chaisemartin and D'Haultfœuille 2020; Strezhnev 2017).
- ▶ The TWFE estimate equals a weighted average of individualistic treatment effects across the treated observations.
- ▶ The idea is similar to that in Aronow and Samii (2016), but the consequence is more severe.
- ▶ Let's denote the collection of treated observations as  $\mathcal{M}$  and untreated ones as  $\mathcal{O}$ .
- ▶ Then,

$$\hat{\tau}_{TWFE} \rightarrow \sum_{it:(i,t) \in \mathcal{M}} w_{it} \tau_{it},$$

where each  $w_{it} = \frac{\tilde{D}_{it}}{\sum_{it:(i,t) \in \mathcal{M}} \tilde{D}_{it}}$  and  $\tilde{D}_{it} = D_{it} - \bar{D}_i - \bar{D}_{.t} + \bar{D}$ .

## Caveats of the TWFE model

- ▶ Consider the following example:

|             |   | Periods |     |     |     |             |
|-------------|---|---------|-----|-----|-----|-------------|
|             |   | 1       | 2   | 3   | 4   | $\bar{D}_i$ |
| Units       | 1 | 0       | 0   | 0   | 0   | 0           |
|             | 2 | 0       | 0   | 0   | 1   | 1/4         |
|             | 3 | 0       | 1   | 1   | 1   | 3/4         |
| $\bar{D}_t$ |   | 0       | 1/3 | 1/3 | 2/3 | 1/3         |

- ▶ We can show that the within estimator,  $\hat{\tau}$ , converges to

$$\frac{11}{12} \left( \frac{1}{2} \tau_{24} + \frac{1}{4} \tau_{32} + \frac{1}{4} \tau_{33} - \frac{1}{12} \tau_{34} \right),$$

- ▶ Some weights can even be negative in practice, making it difficult to interpret the estimate in a causal way.
- ▶ The event study model has the same problem (Abraham and Sun 2018).

## Caveats of the TWFE model

- ▶ The issue is that the TWFE uses all the possible DID estimates in the data:

$$\hat{\tau}_{TWFE} = \frac{\sum_{t=1}^T \sum_{i, D_{it}=1} \sum_{j, D_{jt}=0} \sum_{t' \neq t} [(Y_{it} - Y_{it'}) - (Y_{jt} - Y_{jt'})]}{\sum_{t=1}^T \sum_{i, D_{it}=1} \sum_{j, D_{jt}=0} \sum_{t' \neq t} (1 - D_{it'} + D_{jt'})}$$

- ▶  $(Y_{it} - Y_{it'}) - (Y_{jt} - Y_{jt'})$  goes through all the possible DIDs in the sample.

|      | Time |   |   |      | Time |   |   |      | Time |   |   |
|------|------|---|---|------|------|---|---|------|------|---|---|
| Unit | 1    | 2 | 3 | Unit | 1    | 2 | 3 | Unit | 1    | 2 | 3 |
| 1    | 0    | 1 | 1 | 1    | 0    | 1 | 1 | 1    | 0    | 1 | 1 |
| 2    | 0    | 1 | 1 | 2    | 0    | 1 | 1 | 2    | 0    | 1 | 1 |
| 3    | 0    | 0 | 1 | 3    | 0    | 0 | 1 | 3    | 0    | 0 | 1 |
| 4    | 0    | 0 | 1 | 4    | 0    | 0 | 1 | 4    | 0    | 0 | 1 |
| 5    | 0    | 0 | 0 | 5    | 0    | 0 | 0 | 5    | 0    | 0 | 0 |

Matched controls
Valid second differences
Invalid second differences



## Solutions under staggered adoption

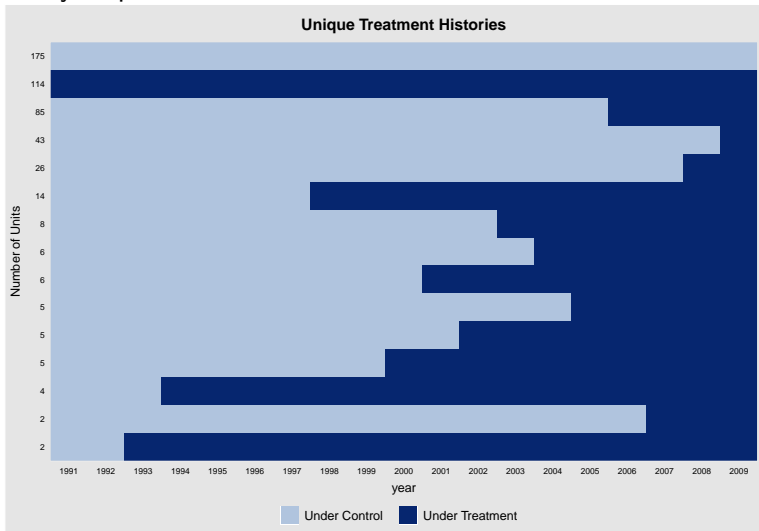
- ▶ As the problem is caused by invalid second differences, a straightforward solution is not to use them in estimation.
- ▶ Define cohort  $t$  as units whose treatment start from period  $t + 1$ .
- ▶ We can estimate the ATT for each cohort as in the multi-period DID.
- ▶ We combine units that are treated only from period  $t$  and units that have not been treated in period  $t$  and obtain a dataset with the DID structure.
- ▶ In the previous example, we compare units 1 or 2 only with unit 5 but not with units 3 or 4.
- ▶ Then, we no longer have the invalid second differences.
- ▶ Finally, we average over cohorts for a consistent estimate of the ATT (Goodman-Bacon 2018; Strezhnev 2017).

## Solutions under staggered adoption

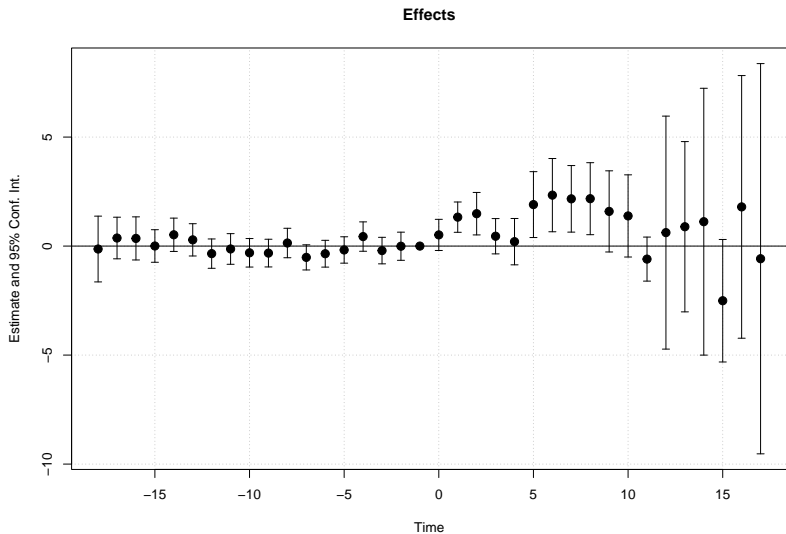
- ▶ In the event study model, Abraham and Sun (2018) propose a similar modification.
- ▶ Instead of just “leads and lags,” we should also control for the interaction between them and the cohort indicators.
- ▶ In other words, we should estimate the effects of “leads and lags” within each cohort and then aggregate across cohorts.
- ▶ These solutions do not work when the treatment switches on and off as we no longer have cohorts.
- ▶ But the key idea still applies: do not use treated observations to estimate any parameter other than  $\tau$ .

# Solutions under staggered adoption: application

- ▶ A key step is to examine the data structure.



# Solutions under staggered adoption: application



## Counterfactual estimation

- ▶ Liu, Wang, and Xu (2020) extend the idea to data with treatment reversal.
- ▶ Remember how the DID estimator works:

$$\begin{aligned}\hat{\tau}_{DID,t} &= \frac{1}{|\mathcal{T}|} \sum_{i \in \mathcal{T}} Y_{it} - \frac{1}{|\mathcal{T}|T_0} \sum_{i \in \mathcal{T}} \sum_{s=1}^{T_0} Y_{is} \\ &\quad - \left( \frac{1}{|\mathcal{C}|} \sum_{i \in \mathcal{C}} Y_{it} - \frac{1}{|\mathcal{C}|T_0} \sum_{i \in \mathcal{C}} \sum_{s=1}^{T_0} Y_{is} \right) \\ &= \frac{1}{|\mathcal{T}|} \sum_{i \in \mathcal{T}} (Y_{it} - \hat{Y}_{it}(0)).\end{aligned}$$

- ▶ We impute the counterfactual for treated observations  $((i, t) \in \mathcal{M})$  using a transformation of the untreated observations  $((i, t) \in \mathcal{M})$ .

## Counterfactual estimation

- ▶ Liu, Wang, and Xu (2020) combine the two-way fixed effects model with the Neyman-Rubin framework and assume that:

$$Y_{it}(0) = \mathbf{X}_{it}\beta + \alpha_i + \xi_t + e_{it},$$

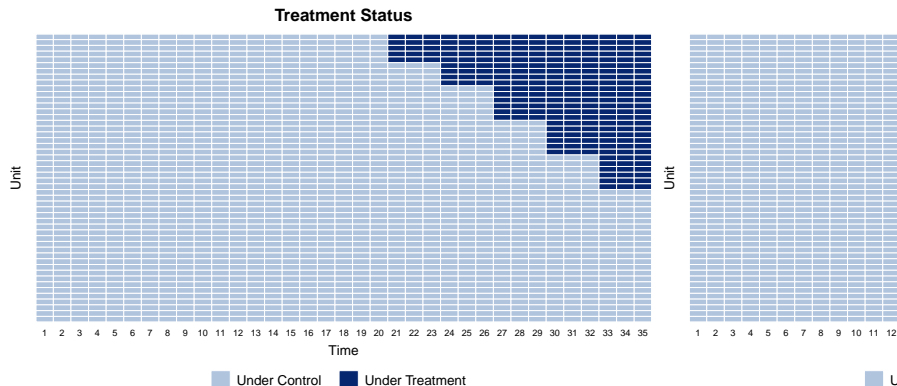
$$Y_{it}(1) = Y_{it}(0) + \tau_{it}.$$

- ▶ We use untreated observations to fit a two-way fixed effects model and employ the model to predict  $Y_{it}(0)$  for each treated observation.
- ▶ Clearly,  $\hat{\tau}_{it} = Y_{it} - \hat{Y}_{it}(0)$  and

$$\hat{\tau}_{ATT} = \frac{1}{|\mathcal{M}|} \sum_{(i,t) \in \mathcal{M}} \tau_{it}.$$

## Counterfactual estimation

- ▶ In a panel setting, treat  $Y(1)$  as missing data
- ▶ Predict  $Y(0)$  based on an outcome model
- ▶ (Use pre-treatment data for model selection)
- ▶ Estimate ATT by averaging differences between  $Y(1)$  and  $\hat{Y}(0)$

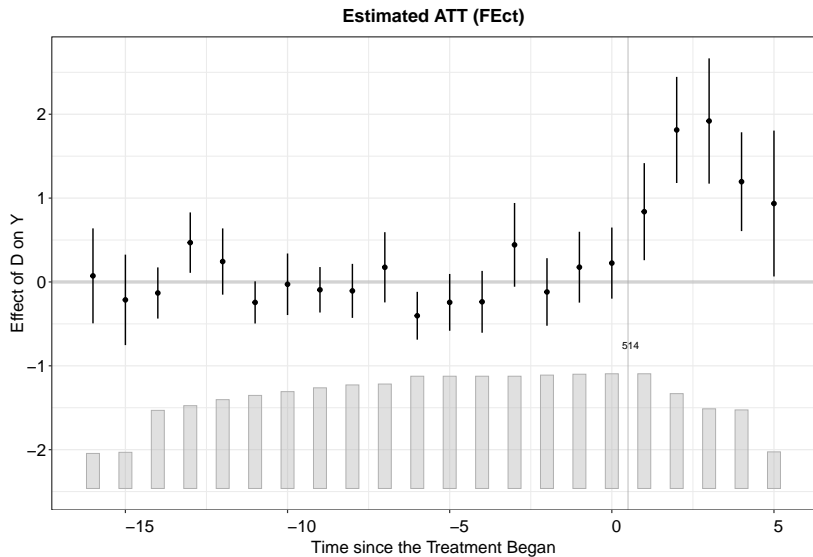


## Counterfactual estimation

- ▶ Liu, Wang, and Xu (2020) show that the estimator is unbiased and consistent for the ATT in each period.
- ▶ The periods are now redefined relative to when the treatment kicks off.
- ▶ It thus avoids the problem of negative weights.
- ▶ It is more straightforward to conduct event study using this method.
- ▶ ATT estimates in the pre-treatment periods provide us a way to examine the assumptions.
- ▶ They rely on block bootstrap to estimate the standard errors and the confidence interval.
- ▶ The framework can incorporate more complicated models.
- ▶ It can be implemented in R with the package *fect*.



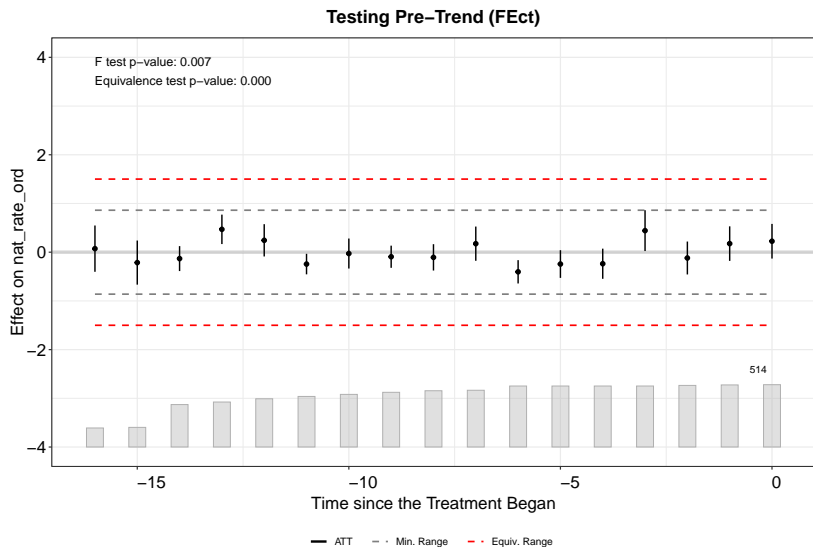
# Counterfactual estimation: application



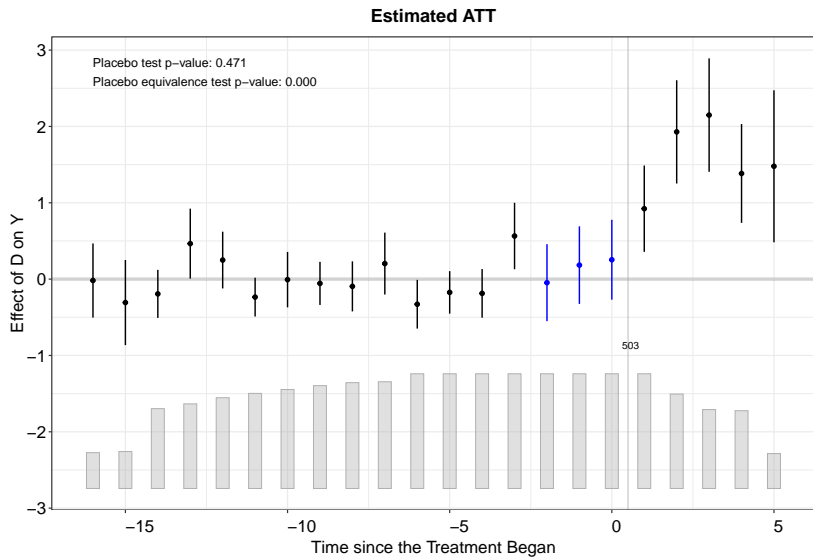
## Test in counterfactual estimation

- ▶ There are tools for practitioners to evaluate the identification assumption rigorously.
- ▶ A placebo test: estimate treatment effects before the treatment's onset and test their significance.
- ▶ Idea: if we apply the estimator to period  $-s$ , then the result should be indistinguishable from zero.
- ▶ An equivalence test: test whether all the pre-treatment ATTs are equal to zero.
- ▶ A test on the violation of SUTVA.

# Test in counterfactual estimation: application



# Test in counterfactual estimation: application



## Counterfactual estimation: caveats

- ▶ We should keep in mind that the validity of this approach relies on a series of assumptions.
- ▶ The model specification has to be correct:
  - ▶ Observable and unobservable confounders are separable.
  - ▶ Observable confounders affect the outcome in a linear and homogeneous manner.
  - ▶ Unobservable confounders have a low-dimensional decomposition.
- ▶ It also requires strict exogeneity and the absence of interference.

## A high-level perspective

- ▶ Arkhangelsky and Imbens (2019) illustrate that under the DGP of the TWFE model, any estimator can be written as a weighting estimator such that:

$$\begin{aligned} \{\hat{w}_{it}\} &= \arg \min \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T \hat{w}_{it}^2, \\ \text{s.t. } \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T \hat{w}_{it} D_{it} &= 1, \frac{1}{N} \sum_{i=1}^N \hat{w}_{it} = 0, \\ \frac{1}{T} \sum_{t=1}^T \hat{w}_{it} &= 0, \hat{w}_{it} D_{it} \geq 0. \end{aligned}$$

- ▶ Then, the causal estimate is

$$\hat{\tau} = \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T \hat{w}_{it} Y_{it}$$

## A high-level perspective

- ▶ The solution of  $\{\hat{w}_{it}\}$  is not unique in data.
- ▶ We can verify that weights generated by the within estimator satisfy conditions 1-3 but not condition 4.
- ▶ This is why we have the problem of negative weights.
- ▶ Meanwhile, weights generated by the counterfactual estimator satisfy all the conditions.
- ▶ This is the result of not using any treated observation to infer the nuisance parameters.

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