

Regression and Balancing

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Linear Methods in Causal Inference
POLI784

Review

- ▶ We introduced another method to account for the influence of confounders, weighting.
- ▶ It is based on the argument of Rosenbaum and Rubin that the propensity score is central for causal inference.
- ▶ It contains all the information from the confounders and should be a balance score.
- ▶ We can estimate the propensity scores with either logistic regression or the CBPS method.
- ▶ Then, we rely on the IPW estimators (HT or HA) to obtain the estimates.
- ▶ Using the estimated propensity scores is more efficient than using the true propensity scores.
- ▶ Ignoring the uncertainty from estimating the propensity scores leads to conservative variance estimates.

Regression

- ▶ Conventionally, we use regression models to control for the influence of confounders.
- ▶ We run the following regression:

$$Y_i = \tau D_i + \mathbf{X}_i' \beta + \varepsilon_i.$$

- ▶ Except for strong ignorability, we also assume that

$$E[Y_i | D_i, \mathbf{X}_i] = \tau D_i + \mathbf{X}_i' \beta$$

- ▶ The impacts from the regressors are additive, linear, and homogeneous.
- ▶ These are structural restrictions that are usually unjustified.

Regression: caveats

- ▶ Remember that when D_i is randomly assigned, controlling \mathbf{X}_i does not cause any bias asymptotically.
- ▶ This is no longer the case when we implement block randomization or assume strong ignorability.
- ▶ Let's assume that

$$Y_i = Y_i(0) + \tau_i D_i,$$

$$E[D_i | \mathbf{X}_i] = \mathbf{X}_i' \eta.$$

- ▶ Aronow and Samii (2016) show that under these conditions,

$$\hat{\tau}_{OLS} \rightarrow \frac{E[w_i \tau_i]}{E[w_i]} \neq E[\tau_i],$$

where $w_i = (D_i - E[D_i | \mathbf{X}_i])^2$.

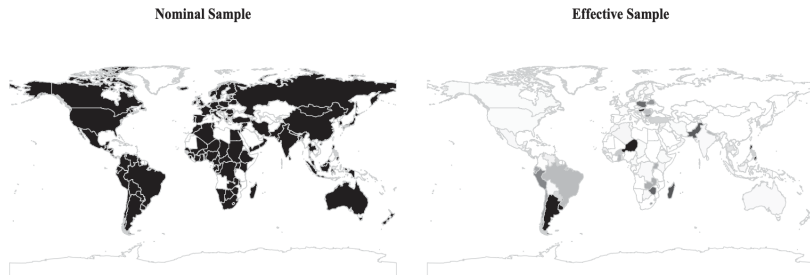
Regression: caveats

- ▶ The OLS estimate converges to a “convex combination” of individualistic treatment effects.
- ▶ In the definition of the SATE, each τ_i has a weight of $\frac{1}{N}$.
- ▶ But in the OLS estimate, the weights vary across the units.
- ▶ In general, $\hat{\tau}_{OLS}$ does not converge to τ unless $\tau_i = \tau$ (homogeneity).
- ▶ Observations have unequal contributions to the estimate.
- ▶ The group in which the treatment varies more drastically is over-weighted in the analysis.
- ▶ Thus, the OLS estimate is not representative of the sample and does not have a higher external validity.
- ▶ Aronow and Samii (2016) define the concept of “effective sample,” the sample re-weighted by each unit’s contribution to the estimate.

Regression: caveats

In the effective sample, each unit has a weight of $\hat{\nu}_i^2$, where $\hat{\nu}_i$ is the residual from regressing D_i on \mathbf{X}_i .

FIGURE 1 Example of nominal and effective samples from Jensen (2003)



Note: On the left, the shading shows countries in the nominal sample for Jensen (2003) estimate of the effects of regime type on FDI. On the right, darker shading indicates that a country contributes more to the effective sample, based on the panel specification used in estimation.

Regression: caveats

- ▶ Regression may prevent you from seeing the failure of positivity.
- ▶ Let's assume that $\tau_i = \tau$ and linearity holds.
- ▶ We fit regression models on both the treatment group and the control group.
- ▶ The regression coefficients will be consistently estimated, and we can calculate the predicted outcome \hat{Y}_i for any unit.
- ▶ Then, we estimate τ by

$$\hat{\tau} = \frac{1}{N_1} \sum_{i=1}^N D_i \hat{Y}_i - \frac{1}{N_0} \sum_{i=1}^N (1 - D_i) \hat{Y}_i.$$

- ▶ It is straightforward to show that

$$E[\hat{\tau}] \rightarrow \tau + (\bar{\mathbf{X}}_1 - \bar{\mathbf{X}}_0)\beta.$$

- ▶ If positivity fails, $\bar{\mathbf{X}}_1 \neq \bar{\mathbf{X}}_0$ and the estimator is inconsistent.

Regression: remedy

- ▶ One solution is to rely on the “counterfactual estimator” (Kline 2011; Heckman, Ichimura, and Todd 1997).
- ▶ We first estimate β using only units in the control group.
- ▶ Then, we predict the counterfactual of each treated unit via

$$\hat{Y}_i(0) = \mathbf{X}_i' \hat{\beta}.$$

- ▶ We estimate τ via

$$\hat{\tau}_{reg} = \frac{1}{N_1} \sum_{i=1}^N D_i \left(Y_i - \hat{Y}_i(0) \right) \rightarrow \tau_{ATT} = \frac{1}{N_1} \sum_{i:D_i=1} \tau_i.$$

- ▶ This estimator does not suffer from the asymptotic bias as we weight the treated units properly.
- ▶ The idea is later generalized to “X-learner” by Künzel et al. (2019) where they use machine learning to predict $\hat{Y}_i(0)$.

Regression: pros and cons

- ▶ Regression requires the correct model specification and relies on extrapolation when positivity fails.
- ▶ We can increase the complexity of the outcome model to reduce the bias caused by treatment effect heterogeneity (Ratkovic 2019).
- ▶ For instance, with one confounder, we can fit two kernel regression models, $\hat{m}_1(X_i)$ and $\hat{m}_0(X_i)$, on the treatment group and the control group, respectively.
- ▶ Then,

$$\hat{\tau}_{reg} = \frac{1}{N} \sum_{i=1}^N [\hat{m}_1(X_i) - \hat{m}_0(X_i)]$$

will be consistent for τ .

- ▶ Regression requires weaker assumptions: $E[\varepsilon_i | \mathbf{X}_i] = 0$.

Regression: application

The OLS estimate is 1794.343

The SE of OLS estimate is 670.9967

The Lin regression estimate is 1583.468

The SE of Lin regression estimate is 678.0574

Regression: application

```
## The regression ATT estimate is 687.8221
```

Balancing

- ▶ Now, consider the outcome model

$$Y_i(0) = \mathbf{X}_i' \beta_0,$$

$$Y_i(1) = \mathbf{X}_i' \beta_1 + \tau_i.$$

- ▶ Suppose we can find a group of weights, $\{w_i\}_{(i:D_i=0)}$, such that

$$\bar{\mathbf{X}}_1 = \sum_{i:D_i=0} w_i \mathbf{X}_i, \text{ and } \sum_{i:D_i=0} w_i = 1$$

- ▶ Then,

$$\bar{Y}_1 - \bar{Y}_0^w = \tau_{ATT} + (\bar{\mathbf{X}}_1 - \bar{\mathbf{X}}_1) \beta = \tau_{ATT},$$

with $\bar{Y}_0^w = \sum_{i:D_i=0} w_i Y_i$.

- ▶ This is an idea known as balancing.

Entropy balancing

- ▶ There are many possible sets of $\{w_i\}_{(i:D_i=0)}$ that satisfy the balance conditions.
- ▶ We choose the set that minimizes a pre-specified criterion, such as the entropy (Hainmueller 2012):

$$\sum_{i:D_i=0} w_i \log w_i.$$

- ▶ This method is thus known as “entropy balancing.”
- ▶ Entropy measures the “uncertainty inherent to the variable’s possible outcomes” (Wikipedia).
- ▶ It has a root in statistical thermodynamics and was introduced by Shannon when he founded the information theory.
- ▶ Entropy can also be seen as the “distance” from the uniform distribution ($w_i = 1/N_0$).
- ▶ The weights can be solved via convex optimization.

Entropy balancing

- ▶ We estimate the ATT via

$$\hat{\tau}_{EB} = \frac{1}{N_1} \sum_{i:D_i=1} Y_i - \sum_{i:D_i=0} \hat{w}_i Y_i$$

- ▶ $\hat{\tau}_{EB}$ is consistent when either the outcome is linear in \mathbf{X}_i or the propensity score model is logistic (Zhao and Percival 2016).
- ▶ We can try to balance higher order moments of \mathbf{X} .
- ▶ The more moments we balance, the more likely we eliminate all the influences of \mathbf{X} .
- ▶ There can be too many choices if \mathbf{X} is also high-dimensional.
- ▶ We need approaches to select moments that matter.
- ▶ This can be done by either kernel balancing (Hazlett 2018) or hierarchically regularized entropy balancing (Xu and Yang 2021).

Kernel balancing

- ▶ In kernel balancing, we calculate the kernel distance between each pair of units.
- ▶ Suppose we use the Gaussian kernel

$$k(\mathbf{X}_i, \mathbf{X}_j) = e^{-\frac{\|\mathbf{x}_i - \mathbf{x}_j\|^2}{2b}},$$

and generate the kernel matrix \mathbf{K} with the (i, j) th element being $k(\mathbf{X}_i, \mathbf{X}_j)$.

- ▶ We find a group of weights $\{w_i\}_{i:D_i=0}$ such that

$$\begin{aligned} \frac{1}{N_1} \sum_{i:D_i=1} k(\mathbf{X}_i, \mathbf{X}_j) &\approx \sum_{i:D_i=0} w_i k(\mathbf{X}_i, \mathbf{X}_j) \\ \sum_{i:D_i=0} w_i &= 1, \end{aligned}$$

for any j .

- ▶ $\{k(\mathbf{X}_i, \mathbf{X}_j)\}_{i \neq j}$ are seen as $N - 1$ covariates of i .

Kernel balancing

- ▶ Hazlett (2018) show that if

$$Y_i = \alpha + \tau_i D_i + \Phi(\mathbf{X}_i)' \beta + \varepsilon_i,$$
$$\langle \Phi(\mathbf{X}_i), \Phi(\mathbf{X}_j) \rangle = k(\mathbf{X}_i, \mathbf{X}_j),$$

then these weights also satisfy

$$\frac{1}{N_1} \sum_{i:D_i=1} \Phi(\mathbf{X}_i) = \sum_{i:D_i=0} w_i \Phi(\mathbf{X}_i).$$

- ▶ For the Gaussian kernel, $\Phi(\mathbf{X}_i)$ encompasses all the continuous functions of \mathbf{X}_i when $N \rightarrow \infty$.
- ▶ Similarly, the balancing stage introduces extra uncertainties which are often ignored in practice (Wong and Chan 2018).

Balancing: application

```
## Converged within tolerance
```

```
## The ebal ATT estimate is 2424.661
```

```
## The SE of ebal ATT estimate is 894.7984
```

Balancing: application

```
##      age education      black  hispanic  married  nodeg
## 25.8162  10.3459  0.8432   0.0595   0.1892   0.7
##      u74      u75
## 0.7081   0.6000

##      age education      black  hispanic  married
## 34.8506  12.1169  0.2506   0.0325   0.8663
##      re75      u74      u75
## 19063.3377  0.0863  0.1000

##      age education      black  hispanic  married  nodeg
## 25.8162  10.3459  0.8432   0.0595   0.1892   0.7
##      u74      u75
## 0.7081   0.6000
```

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